

Introduction to Algorithms and Data Structures

Lecture 27: Dealing with NP-completeness (Approximation algorithms)

Mary Cryan

School of Informatics
University of Edinburgh

Implications of NP-complete status

When prove a problem is NP-complete, we no longer expect to be able to design polynomial-time algorithms to generate exact solutions (to the Decision problem or to an Optimization version)

What are our options?

- ▶ Heuristic methods (“rules of thumb”) that might not *guarantee* good results, but behave well in practice.
- ▶ Might there be a polynomial-time algorithm to search for an *approximate* solution rather than an exact one? (today)
- ▶ Brute-force methods that run in exponential-time (L28)
- ▶ Recursive backtracking (L28)

We might use *randomness* ... and may later want to *de-randomize*.

Mostly we are dealing with the *optimization* version of the decision problem.

What is an approximation algorithm?

For an *optimization problem*, we ask questions of the form

“For a given instance \mathcal{J} of the problem, what is the value of a **best** solution y for that instance?”

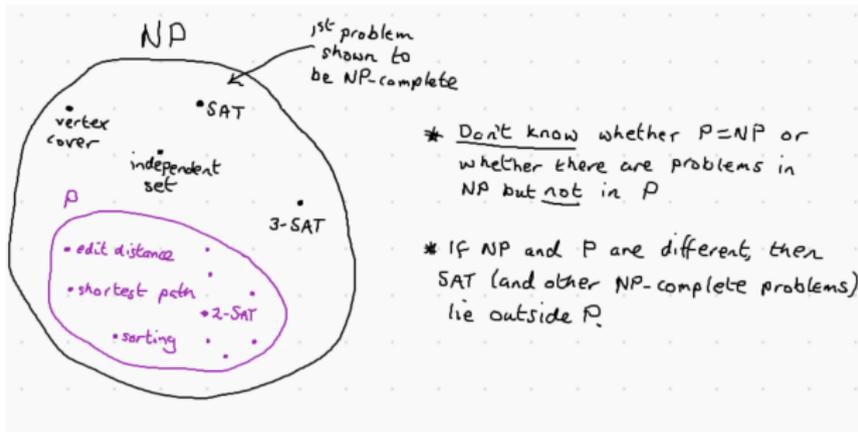
best will usually either be

- ▶ **max**-valued (eg Ind.Set, solutions being Ind.Sets.) or
- ▶ **min**-valued (eg Edit distance, solutions being alignments).

Definition: Consider some **optimization** problem OPT where for a given instance \mathcal{J} , and the set of feasible solutions y , $\text{OPT}(\mathcal{J})$ is the cost/value of the optimum y . An algorithm A is said to be an α -approximation algorithm for OPT if for every instance \mathcal{J} , the algorithm returns a value $A(\mathcal{J})$ satisfying

$$A(\mathcal{J}) \begin{cases} \leq & \alpha \cdot \text{OPT}(\mathcal{J}) & \text{if } \text{OPT} \text{ is a minimization problem} \\ \geq & \alpha^{-1} \cdot \text{OPT}(\mathcal{J}) & \text{if } \text{OPT} \text{ is a maximization problem} \end{cases}$$

Polynomial-time approximation: examples



Vertex Cover Will see a simple algorithm which gives a 2-approximation.

MAX 3-SAT Will see a randomized algorithm (and a derandomization) that gives a $\frac{8}{7}$ -approximation for satisfying a max number of clauses.

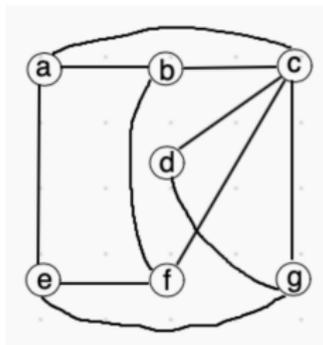
note: The α -value is called the **approximation ratio** of the algorithm.

Vertex Cover (minimization)

Definition

Given an undirected graph $G = (V, E)$, a subset $V' \subseteq V$ is a **Vertex Cover (VC)** for G if every edge $e \in E$ has at least one endpoint in V' .

VERTEX COVER: Determine the size of the minimum cardinality VC for G .



Optimum VC has size 4 (c, 1 of $\{d, g\}$, 2 non-adjacent vertices of $\{a, b, f, e\}$).

2-approximation for Vertex Cover

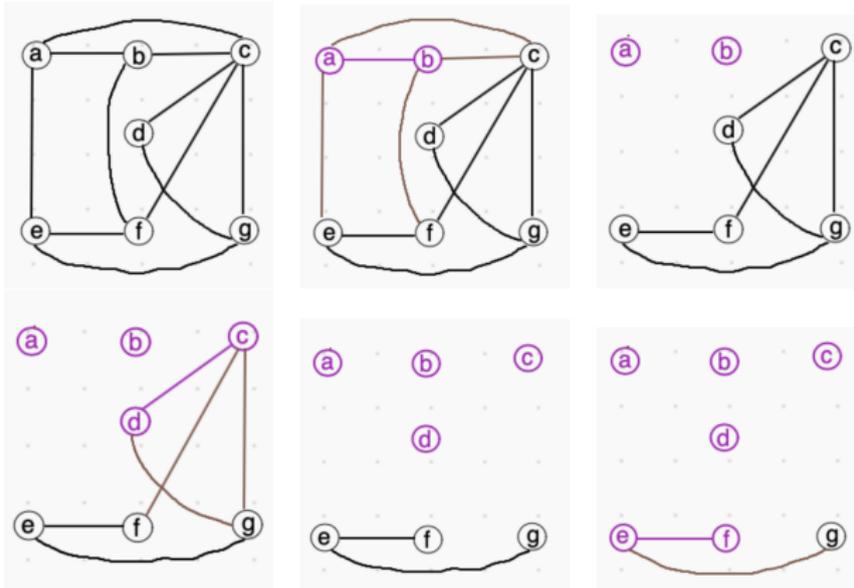
The decision version of VERTEX COVER (is the minimum VC of size $\leq k$) is NP-complete \Rightarrow we do not believe that the optimization VERTEX COVER problem can have a polynomial-time algorithm.

Here is an *approximation algorithm*:

Algorithm Apprx-Vertex-Cover($G = (V, E)$)

1. $C \leftarrow \emptyset$
2. $E' \leftarrow E$
3. **while** $E' \neq \emptyset$
4. **do** take any edge $(u, v) \in E'$
5. $C \leftarrow C \cup \{u, v\}$ // add **both** u and v to the cover
6. Remove every edge g with u or v endpoint from E'
7. Print("There is a VC of size ", $|C|$)

2-approximation for Vertex Cover: example



We end up with a VC of size 6.

2-approximation for Vertex Cover

Algorithm Approx-Vertex-Cover($G = (V, E)$)

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6. Remove every edge g with u or v endpoint from E'

Why a 2-approximation?

- ▶ Compare to some unknown minimum vertex cover C^* .
- ▶ Consider the set F of all edges chosen by line 4 (the “purple edges”).
 - ▶ Each $f \in F$ must have *one endpoint* in C^* .
For $f, f' \in F, f \neq f', f$ and f' share *no* endpoints. So $|C^*| \geq |F|$.
 - ▶ The alg chooses each f to have no overlapping endpoints with the earlier purple edges. So $|C| = 2|F|$. Hence $|C| \leq 2|C^*|$.

Optimization/search problem MAX 3-SAT

MAX 3-SAT: Given a 3-CNF formula $\phi = C_1 \wedge \dots \wedge C_m$ over the variables $\{x_1, \dots, x_n\}$, determine the **maximum** number of clauses k such that there is an assignment of binary values to $\{x_1, \dots, x_n\}$ that makes k clauses satisfied.

3-SAT is NP-complete \Rightarrow we do not expect a polynomial-time algorithm to **exactly** solve the MAX 3-SAT problem. **Why?**

We will design an algorithm to find an assignment satisfying $\geq \frac{7}{8} \cdot m$ clauses.

- ▶ Will show we are *guaranteed* there is some assignment satisfying $\geq \frac{7}{8} \cdot m$ clauses \Rightarrow get an $\frac{8}{7}$ -approximation algorithm for MAX 3-SAT.
- ▶ In fact, for optimizing the *value*, we could just output $\frac{7}{8} \cdot m$ without checking anything ... this would already be a $\frac{8}{7}$ -approximation algorithm.
- ▶ Search problem: **find** an assignment to satisfy a high number of clauses.
- ▶ We assume/require a 3-CNF formula where each clause C_j has *exactly* 3 literals (on different logical variables). Need this condition.

Uniform Random Assignment and MAX 3-SAT

We are given $\phi = C_1 \wedge C_2 \wedge \dots \wedge C_m$, and each of the C_j is $(l_{j,1} \vee l_{j,2} \vee l_{j,3})$ for three *literals* over $\{x_1, \dots, x_n\}$ (for example, $(x_4 \vee \bar{x}_1 \vee \bar{x}_9)$).

want: *assignment* to the $\{x_1, \dots, x_n\}$ which satisfies a high number of clauses.

Consider a single clause $C_j = (l_{j,1} \vee l_{j,2} \vee l_{j,3})$

- ▶ C_j is satisfied if *at least one* of its literals are satisfied: $l_{j,1}$ or $l_{j,2}$, or $l_{j,3}$
- ▶ C_j will fail to be satisfied *only if* all its literals are False.
- ▶ Suppose we generate a **uniform random assignment (uar)** to the logical variables x_1, \dots, x_n (each x_i gets 0/1 with probability $\frac{1}{2}$).
 - ▶ The probability that C_j is *not* satisfied is exactly $\frac{1}{2} \cdot \frac{1}{2} \cdot \frac{1}{2}$, ie, $\frac{1}{8}$.
 - ▶ This is where we use the assumption that each clause has 3 literals over different x_i .
 - ▶ The probability that C_j is satisfied is exactly $\frac{7}{8}$.

The **expected number** of clauses of ϕ satisfied by a uar assignment is $\frac{7}{8}m$.

Uniform Random Assignment and MAX 3-SAT

$$\phi = C_1 \wedge C_2 \wedge \dots \wedge C_m$$

Let Y_j be the 0/1 random variable that is 1 if C_j is satisfied.

Then $Y = \sum_{j=1}^m Y_j$ is the number of clauses that are satisfied by the assignment.

The **expected number** of clauses $E[Y]$ satisfied by a uar assignment is $\frac{7}{8}m$ (by *linearity of expectation*)

- ▶ Must be *at least one* assignment to $\mathbf{x} = x_1 \dots x_n$ which satisfies $\geq \frac{7}{8}m$ clauses.
 - ▶ If *all* assignments to the variables satisfied $< \frac{7}{8}m$ clauses, the *expected* number could not be $\frac{7}{8}m$. (under uar random assignment, the *expectation* is the *average* over all $\{0, 1\}^n$).
- ▶ Naïve (randomized) algorithm: generate a random assignment $b \in \{0, 1\}^n$ until we achieve $\geq \frac{7}{8}m$ satisfied clauses.

De-randomized $\geq \frac{7}{8}m$ algorithm for MAX 3-SAT

$$\phi = C_1 \wedge C_2 \wedge \dots \wedge C_m$$

$Y = \sum_{j=1}^m Y_j$ the number of clauses that are satisfied by the var assignment.

$$\begin{aligned} \mathbb{E}[Y] &= \frac{1}{2^n} \sum_{\mathbf{x} \in \{0,1\}^n} \sum_{j=1}^m Y_j \\ &= \frac{1}{2^{n-1}} \sum_{\mathbf{x} \in \{0,1\}^{n-1}} \sum_{j=1}^m \left(\frac{(Y_j |_{x_1=0})}{2} + \frac{(Y_j |_{x_1=1})}{2} \right) \\ &= \frac{\mathbb{E}[Y |_{x_1=0}]}{2} + \frac{\mathbb{E}[Y |_{x_1=1}]}{2} \end{aligned}$$

Observe: If $\mathbb{E}[Y] \geq \frac{7}{8}m$, then *either* $\mathbb{E}[Y | x_1 = 0] \geq \frac{7}{8}m$ or $\mathbb{E}[Y | x_1 = 1] \geq \frac{7}{8}m$.

Idea: Compute $\mathbb{E}[Y | x_1 = 0]$ and $\mathbb{E}[Y | x_1 = 1]$ (how?), compare values, fix x_1 to have that maximizing binary value ... iterate.

De-randomized $\geq \frac{7}{8}m$ algorithm for MAX 3-SAT

"Method of conditional expectations"

Algorithm Greedy-3-SAT(ϕ, n, m)

1. **for** $i = 1, \dots, n$
2. Compute $Exp_0 \leftarrow E[Y \mid x_1 = b_1 \dots x_{i-1} = b_{i-1}, x_i = 0]$
3. Compute $Exp_1 \leftarrow E[Y \mid x_1 = b_1 \dots x_{i-1} = b_{i-1}, x_i = 1]$
4. **if** $Exp_0 \geq Exp_1$
5. **then** $b_i \leftarrow 0$; Update ϕ by fixing $x_i = 0$
6. **else** $b_i \leftarrow 1$; Update ϕ by fixing $x_i = 1$
7. **return** \mathbf{b}

Computing the Exp_0, Exp_1 values:

- ▶ After fixing b_1, \dots, b_{i-1} , $\phi(b_1, \dots, b_{i-1})$ will have some **already satisfied clauses**, some **already failed clauses**, and some **unresolved clauses** of lengths 1, 2, and 3.
- ▶ Evaluate Exp_0 by setting $x_i = 0$. For any C_j with $\bar{x}_i \in C_j$, $E[Y_j \mid \dots x_i = 0] = 1$. For any C_j with $x_i \in C_j$, $E[Y_j \mid \dots]$ drops from $\frac{7}{8} \rightarrow \frac{3}{4}$, from $\frac{3}{4} \rightarrow \frac{1}{2}$, or $\frac{1}{2} \rightarrow 0$.
- ▶ Evaluation of Exp_1 is symmetric.

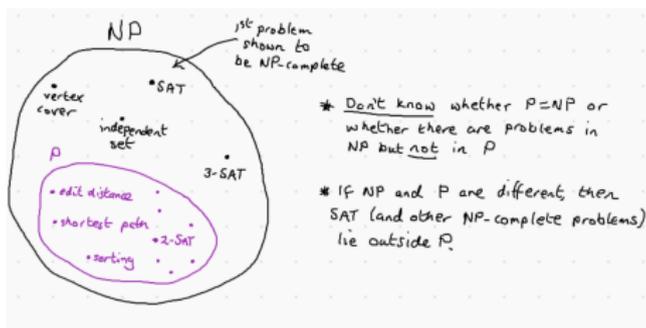
De-randomized $\geq \frac{7}{8}m$ algorithm for MAX 3-SAT

At every iteration of Greedy-3-SAT, we have

$$\begin{aligned} E[Y \mid x_1 = b_1 \dots x_{i-1} = b_{i-1}] &= \frac{E[Y \mid x_1 = b_1 \dots x_{i-1} = b_{i-1}, x_i = 0]}{2} \\ &+ \frac{E[Y \mid x_1 = b_1 \dots x_{i-1} = b_{i-1}, x_i = 1]}{2} \end{aligned}$$

- ▶ At every iteration we assign x_i to have the maximizing binary value b_i .
- ▶ We eventually obtain a assignment $\mathbf{x} \leftarrow \mathbf{b} \in \{0, 1\}^n$ that is **guaranteed to satisfy** $\geq \frac{7}{8}m$ clauses. This is **deterministic**, randomness has been removed.
- ▶ $\frac{8}{7}$ -approximation for the MAX 3-SAT **search** problem.
- ▶ Greedy-3-SAT does n iterations, doing $O(1)$ work for each clause C_j on that iteration $\Rightarrow O(n \cdot m)$ running-time.
- ▶ In 1997, Johan Håstad proved that if $P \neq NP$, then no polynomial-time algorithm can guarantee a better approximation ratio for MAX 3-SAT.

Wrapping up



Vertex Cover 2-approximation in polynomial-time.

MAX 3-SAT $\frac{8}{7}$ -approximation (best possible) in polynomial-time.

Ind.Set. The MAX-IND-SET problem cannot be approximated to any constant approximation factor α (assuming $P \neq NP$).

*All NP-complete problems can be **reduced** to one another. However, the reductions typically do not preserve approximation ratios.*

Reading and Working

Reading:

CLRS Section 35 “intro”, 35.1 (Vertex Cover), 35.4 (MAX 3-SAT)

KT Alternatively, you can read 13.3, 13.3 of Kleinberg and Tardos.

Working: Run Greedy-3-SAT on the following formula:

$$\begin{aligned} \Phi = & (x_1 \vee \bar{x}_2 \vee \bar{x}_3) \wedge (x_1 \vee x_2 \vee \bar{x}_3) \wedge (\bar{x}_1 \vee \bar{x}_2 \vee x_3) \wedge (\bar{x}_1 \vee x_2 \vee x_3) \\ & \wedge (x_1 \vee x_2 \vee \bar{x}_4) \wedge (x_1 \vee \bar{x}_2 \vee x_4) \wedge (x_2 \vee \bar{x}_3 \vee \bar{x}_4). \end{aligned}$$